

DESCRIPTION

MICROMECHANICAL POTENTIAL SENSOR

5 TECHNICAL FIELD

The present invention relates to a potential sensor of non-contact type which can be easily prepared by a MEMS (micro electro mechanical systems) technology, and an image forming apparatus and a
10 potential measuring method utilizing such potential sensor.

BACKGROUND ART

As a sensor for measuring a surface potential of a measured object, there is already known a
15 variable capacitance potential sensor of mechanical type. Fig. 9 shows a principle of the variable capacitance potential sensor of mechanical type. A measured object 1099 has a potential V relative to a
20 ground potential. A detection electrode 1021 is provided in an opposed relationship thereto, and a movable shutter 1025 is provided immediately above the detection electrode 1021. When the movable shutter 1025 moves, an electrostatic capacitance C
25 between the measured object 1099 and the detection electrode 1025 shows a variation. In the detection electrode 1021, a charge Q is induced according to V

and C. A current flowing between the detection electrode 1021 and the ground is detected by an ammeter 1060. As the charge Q induced in the detection electrode 1021 is given by $Q = CV$, a
5 current flowing in the ammeter 1060 at a time t is given by $i = dQ/dt = VdC/dt$, and the potential V can be obtained if dC/dt is known. The dC/dt is a sensitivity of this sensor, and, as will be apparent from this relation, the sensitivity can be elevated
10 by increasing the difference between the maximum and minimum values of C or reducing the time t of variation.

Such variable capacitance potential sensor of mechanical type, obtainable with the MEMS technology,
15 is for example known in a following type (cf. USP No. 6,177,800). Fig. 10 illustrates a potential sensor 1001, which is constituted by a driver component 1010 and a sensor component 1020. These components can be prepared by the MEMS technology on a substrate 1004.

20 The driver component 1010 is formed by a suspension 1018 having a parallel hinge structure, and a comb-shaped electrostatic actuator 1012. The comb-shaped electrostatic actuator 1012 is a common mechanism for electrostatically driving a micro
25 structure, and is constituted by a movable electrode 1013 supported by the suspension 1018 and a fixed electrode 1014 mounted on the substrate 1004. The

comb-shaped electrostatic actuator 1012 is electrically connected to an electrostatic drive signal source 1050. The movable electrode 1013 is supported by the suspension 1018 so as to be movable in a lateral direction in the drawing. The comb-shaped electrodes of the movable electrode 1013 and those of the fixed electrode 1014 are mutually meshing and an electrostatic attractive force is exerted therebetween when a potential difference is given.

The driver component 1010 is connected to the sensor component 1020. A detection electrode assembly 1021 is fixed to the substrate 1004 and is capable of a capacitative coupling with a measured surface. The detection electrode assembly 1021 is constituted by a set of mutually separated individual detection electrodes (represented by 1021a, 1021b, 1021c). Individual detection probes are connected together, so that the individual signals are combined (superposed). The sensor component 1020 is further provided with a movable shutter 1025, which selectively covers the detection electrode assembly 1021. The movable shutter 1025 is mechanically connected to the driver component 1010, of which a linear displacement induces a corresponding displacement of the movable shutter 1025.

The movable shutter 1025 is provided with

plural apertures 1024, which are so constructed as to selectively expose the detection electrode assembly 1021 through the apertures 1024 when the movable shutter 1025 is in a first position. The apertures 1024 are mutually separated by a distance corresponding to a distance between the detection electrodes. When the movable shutter 1025 is in a second position, the detection electrode assembly 1021 is covered by mask portions 1026 present between the apertures 1024. Stated differently, when the movable shutter 1025 is in the first position, the capacitive coupling by the detection electrode assembly 1021 is enabled. On the other hand, when the movable shutter 1025 is in the second position, the detection electrode assembly 1021 is masked and prevented from the capacitive coupling. A current generated in the detection electrode assembly is outputted to a lead electrode 1028 and is amplified by an amplifier 1060.

However, in the MEMS potential sensor of the aforementioned structure, the detection sensitivity cannot be made sufficiently high because an effective area of the detection electrode cannot be made large as will be explained in the following with reference to Fig. 11. The detection sensitivity dC/dt of the potential sensor is proportional to the effective area of the detection electrode. Fig. 11 is a cross-

sectional view along a line 11-11 in Fig. 10. Let it be assumed that a detection electrode 1021 has a width $W1$, an interval between the detection electrodes is a length $W2$, an aperture 1024 has a width $W3$, and a mask portion 1026 has a width $W4$. In order that the detection electrode can be exposed completely, width $W3$ of the aperture has to be equal to or larger than width $W1$ of the electrode ($W3 \geq W1$). In order that the detection electrode can be masked completely, first, width $W4$ of the mask portion has to be equal to or larger than width $W1$ of the electrode ($W4 \geq W1$). In addition, the interval $W2$ has to be equal to or larger than width $W3$ of the aperture. On the other hand, a condition of the widths for efficiently exposing and masking the detection electrode with a minimum moving distance of the movable shutter is given by setting up the widths and interval equal to one another. Consequently, widths $W1$ and $W2$ are almost equal to each other so that the effective area of the detection electrodes has been limited to about a half of an occupied area on the substrate.

The present invention has been made in consideration of the aforementioned situation.

DISCLOSURE OF THE INVENTION

According to an aspect of the present invention,

there is provided that a potential sensor comprising first and second detection electrodes opposed to a potential-measured object of which a potential is to be measured, and a movable shutter so positioned
5 between the detection electrodes and the potential-measured object with gaps thereto; wherein the movable shutter can assume a first state and a second state, the first detection electrode is exposed to the potential-measured object wider when the movable
10 shutter assumes the first state than when the movable shutter assumes the second state, and the second detection electrode is exposed to the potential-measured object narrower when the movable shutter assumes the first state than when the movable shutter
15 assumes the second state. Such configuration allows to increase the effective area of the detection electrodes since the first and second detection electrodes can be positioned closer, and to increase the sensitivity for a given size, as a signal is
20 obtained by a differential processing of outputs of the electrodes. Also it can be realized in a smaller size for a same sensitivity, thus allowing a compact structure and a cost reduction.

The potential sensor preferably comprises a
25 substrate, first and second detection electrode assemblies of which at least either one is formed in plural parts and which are provided on the substrate,

and at least one movable shutter on the two sets of the detection electrode assemblies with a gap thereto, wherein the first detection electrode assembly is exposed to a potential-measured object wider when the movable shutter assumes a first state than when the movable shutter assumes a second state, and the second detection electrode assembly is exposed to the potential-measured object narrower when the movable shutter assumes the first state than when the movable shutter assumes the second state. Though each of the first and second detection electrodes may be formed by a single part, the structure of such configuration allows to further increase the effective area of each detection electrode.

In the potential sensor, the movable shutter is preferably elastically supported movably between the first state and the second state. Thereby there can be realized a movement of the movable shutter not hindered by a friction. A drive frequency of the potential sensor is preferably substantially equal to a mechanical resonance frequency of the movable shutter. Thereby an electric power consumption for obtaining a given amplitude can be significantly reduced.

In the potential sensor, the movable shutter is preferably so constituted as to be controlled by a magnetic field generation means which generates a

magnetic field substantially perpendicularly to a movable direction of the movable shutter and a current application means which supplies the movable shutter with a current substantially perpendicularly to the movable direction of the movable shutter and to a direction of the magnetic field, thereby assuming the first state and the second state. The magnetic field generation means is preferably a permanent magnet or an electromagnetic coil. Such configuration, in which the movable shutter itself comprises a part of an actuator, does not require preparation of a separate actuator unit and can therefore be realized compactly. Also in case plural movable shutters are provided, each movable shutter can be operated individually, thereby reducing the mass of a movable part and increasing the operating speed to elevate the sensitivity of the sensor. Also the driver can be realized with a lower cost as a high voltage is not required in driving.

20 The potential sensor preferably comprises two or more movable shutters and at least two current application means which supplies the movable shutters with currents substantially perpendicularly to the moving directions of the movable shutter, whereby the first state and the second state can be assumed by an interaction of the currents supplied to the movable shutters. Since the movable shutter itself comprises

a part of an actuator also in this configuration, a separate actuator unit need not be prepared and a compact configuration can be realized. Also since each movable shutter can be operated individually, it is possible to reduce the mass of a movable part and to increase the operating speed thereby elevating the sensitivity of the sensor. Also the driver can be realized with a lower cost as a high voltage is not required in driving.

10 According to another aspect of the present invention, there is provided an image forming apparatus comprising the potential sensor and an image forming means which controls an image formation based on an output of the potential sensor. Such configuration allows to provide an image forming apparatus exploiting the features of the potential sensor. The image forming means has, for example, a copying function, a printing function or a facsimile function. Also the image forming means can be realized in a configuration including a photosensitive drum, in which a charged potential of the photosensitive drum is measured by the aforementioned potential sensor provided in an opposed relationship to the photosensitive drum.

25 According to a further aspect of the present invention, there is provided a potential measuring method comprising: a step of positioning a potential

sensor including first and second electrodes and a movable shutter for selectively masking the two electrodes, in which the movable shutter can assume a first state and a second state, the first electrode is exposed wider when the movable shutter assumes the first state than when the movable shutter assumes the second state, and the second electrode is exposed narrower when the movable shutter assumes the first state than when the movable shutter assumes the second state, and a potential-measured object in such a manner that the movable shutter is positioned between the potential sensor and the potential-measured object; and a step of switching the movable shutter between the first state and the second state, and measuring a potential of the potential-measured object based on a change in an electrostatic capacitance generated between the first and second electrodes and the potential-measured object.

According to the present invention, it is rendered possible to increase the area of the detection electrode, in comparison with that in the prior potential sensor utilizing the MEMS technology. It is therefore possible to improve the sensitivity for a same dimension as in the prior technology, or to reduce the dimension for a same sensitivity as in the prior technology. It is also possible to reduce the production cost by increasing a number of sensors

per a silicon wafer.

BRIEF DESCRIPTION OF THE DRAWINGS

Fig. 1 is a plan view of a potential sensor of
5 an example 1 of the present invention.

Figs. 2A and 2B are views showing function of
the potential sensor of the example 1.

Fig. 3 is an exploded perspective view of a
potential sensor of an example 2 of the present
10 invention.

Figs. 4A and 4B are views showing function of
the potential sensor of the example 2.

Fig. 5 is an exploded perspective view of a
potential sensor of an example 3 of the present
15 invention.

Figs. 6A and 6B are views showing function of
the potential sensor of the example 3.

Figs. 7A and 7B are views showing function of
the potential sensor of an example 4.

Fig. 8 is a schematic view of an image forming
20 apparatus of an example 5 of the present invention.

Fig. 9 is a view showing a general operation
principle of a prior potential sensor of mechanical
type.

Fig. 10 is a view showing a prior MEMS
25 potential sensor.

Fig. 11 is a view showing drawbacks in the

prior MEMS potential sensor.

BEST MODE FOR CARRYING OUT THE INVENTION

In the following, in order to clarify
5 embodiments of the present invention, specific
examples will be explained with reference to
accompanying drawings. In the drawings, arrows
referred to by numbers having a hundred digit of 8,
e.g. 841 in Fig. 4A and 874 in Fig. 7B, mean
10 directions of currents, respectively, and non-relief
arrows referred to by numbers having a hundred digit
of 9, e.g. 941 in Fig. 4A and 974 in Fig. 7B, mean
directions of movements of portions, respectively.

(Example 1)

15 Fig. 1 is a plan view of a potential sensor of
Example 1, and Figs. 2A and 2B are cross-sectional
views thereof. A potential sensor 101 is formed by a
driver component 110 and a sensor component 120.
These are formed by a MEMS technology on a substrate
20 104.

The driver component 110 is formed by a
suspension 118 having a parallel hinge structure, and
a comb-shaped electrostatic actuator 112. The comb-
shaped electrostatic actuator 112 is a common
25 mechanism for electrostatically driving a micro
structure, and is composed of a movable electrode 113
supported by the suspension 118 and a fixed electrode

114 mounted on the substrate 104. The comb-shaped electrostatic actuator 112 is electrically connected to an electrostatic drive signal source 150. The movable electrode 113 is supported by the suspension 5 118 so as to be movable in a lateral direction in the drawing. The comb-shaped electrodes of the movable electrode 113 and those of the fixed electrode 114 are mutually meshing and an electrostatic attractive force is exerted therebetween when a potential 10 difference is given. This structure is same as in the prior potential sensor explained in the foregoing.

The driver component 110 is connected to the sensor component 120. Detection electrode assemblies 121a, 121b featuring the present example are fixed to 15 the substrate 104, and each is capable of a capacitative coupling with a surface to be measured. The detection electrode assemblies 121a, 121b are comprised of sets of mutually distanced individual detection electrodes. The detection electrodes of 20 each set are electrically connected. Also the individual detection electrodes of the detection electrode assemblies 121a, 121b are arranged with such gaps as not to cause electrical shortcircuiting.

A movable shutter 125 selectively covers the 25 detection electrode assemblies 121a, 121b. The movable shutter 125 is mechanically connected to the driver component 110, of which a linear displacement

induces a corresponding displacement of the movable shutter 125.

The movable shutter 125 is provided with plural apertures 124. When the movable shutter 125 is in a first position (a position moved to the right in Fig.1), the detection electrode assembly 121a is exposed through the apertures 124, while the detection electrode assembly 121b is masked (cf. Fig. 2A). Also when the movable shutter 125 is in a second position (a position moved to the left in Fig.1), the detection electrode assembly 121a is masked, while the detection electrode assembly 121b is exposed through the apertures 124 (cf. Fig. 2B).

Stated differently, when the movable shutter 125 is in the first position, the detection electrode assembly 121a forms a capacitative coupling with an object of which potential is to be measured (hereinafter called "measured object"), and, when the movable shutter 125 is in the second position, the detection electrode assembly 121b forms a capacitative coupling with the measured object. Currents generated by the detection electrode assemblies 121a, 121b are respectively outputted to lead electrodes 122a, 122b and are subjected to a differential amplification by a differential amplifier 160 to provide a sensor output.

In the aforementioned configuration, it is

possible, by selecting the drive frequency of the movable shutter 125 substantially same as a mechanical resonance frequency, to reduce an electric power required for driving thereby alleviating the
5 burden of the driver component 110.

In the present example, as the detection electrode assemblies 121a, 121b are arranged with small gaps on the substrate 104, an effective area of the detection electrodes can be approximately doubled
10 in comparison with the prior potential sensor utilizing the MEMS technology. It is therefore possible to improve the sensitivity for a same dimension as in the prior technology, or to reduce the dimension for a same sensitivity as in the prior
15 technology. It is also possible to reduce the production cost by increasing a number of sensors per a silicon wafer.

(Example 2)

Fig. 3 is an exploded perspective view of a potential sensor of an example 2. On a substrate 204,
20 detection electrode assemblies 221a, 221b, lead electrodes 222a, 222b for detection electrodes, and driving lead electrodes 233a, 233b are formed by patterning. The detection electrode assemblies 221a,
25 221b are comprised of sets of mutually distanced individual detection electrodes, and the detection electrodes of each set are electrically connected by

the lead electrode 222a or 222b for the detection electrodes. Also the individual detection electrodes of the detection electrode assemblies 221a, 221b are arranged with such gaps as not to cause electrical shortcircuiting. Movable shutter units 210a to 210d are formed by mask members 211a to 211d, parallel hinge suspensions 212a to 212d and fixed members 213a to 213d, which are integrally formed with conductive materials. In the present example, the driving lead electrodes 223a, 223b are fixedly coupled with the fixed members 213a to 213d. The mask members 211a to 211d are supported by the parallel hinge suspensions 212a to 212d on the detection electrode assemblies 221a, 221b with a gap thereto. Under the substrate 204, a permanent magnet 230 is positioned to generate a magnetic flux in a direction perpendicular to the substrate 204. The driving lead electrodes 223a, 223b are electrically connected to a driver 250, while the lead electrodes 222a, 222b for the detection electrodes are electrically connected with a differential amplifier 290.

Now the function of the potential sensor of the above-described configuration will be explained. Fig. 4A is a plan view of the present example. A measured object is positioned in a substantially perpendicular direction opposed to the substrate 204. In such state, when a current 841 is generated from the

driver 250 as shown in Fig. 4A and is made to flow from the driving lead electrode 223a to 223b through the movable shutter units 210a to 210d, because of the presence of a magnetic field by permanent magnet 230 in a direction from the reverse side of the plane of the drawing to the observe thereof, the parallel hinge suspensions 212a to 212d are bent and the mask members 211a to 211d move to the right in the drawing (arrow 941). As a result, the detection electrode assembly 221a is exposed to increase an electrostatic capacitance between the detection electrode assembly 221a and the measured object, while the detection electrode assembly 221b is masked to decrease an electrostatic capacitance between the detection electrode assembly 221b and the measured object.

Inversely, when a current 842 is made to flow, as shown in Fig. 4B, in a direction from the driving lead electrode 223b to 223a, the mask members 211a to 211d move to the left in the drawing (arrow 942). As a result, the detection electrode assembly 221b is exposed to increase an electrostatic capacitance between the detection electrode assembly 221b and the measured object, while the detection electrode assembly 221a is masked to decrease an electrostatic capacitance between the detection electrode assembly 221a and the measured object.

By repeating the above-described operations,

charges of mutually opposite phases are induced in the detection electrode assemblies 221a, 221b and are subjected to a differential amplification by the differential amplifier 290, whereby the potential of the measured object can be measured.

It is possible, by selecting the drive frequency of the movable shutter units 210a to 210d substantially equal to a mechanical resonance frequency, to reduce an electric power required for driving.

Also in the present example, it is possible to increase the area of the detection electrodes. It is therefore possible to improve the sensitivity for a same dimension as in the prior technology, or to reduce the dimension for a same sensitivity as in the prior technology. It is also possible to reduce the production cost by increasing a number of sensors per a silicon wafer.

Also the present example, since the movable shutter itself comprises a part of an actuator, does not require preparation of a separate actuator unit and can therefore be realized compactly. It is therefore possible to improve the sensitivity for a same dimension as in the prior technology, or to reduce the dimension for a same sensitivity as in the prior technology. It is naturally possible also to reduce the production cost by increasing a number of

sensors per a silicon wafer.

Also since each movable shutter moves individually, it is possible to reduce the mass of the movable part and to increase the operation speed, thereby improving the sensitivity. Also, in comparison with Example 1, a high voltage is not required for driving, so that the driver can be realized with a lower cost.

(Example 3)

Fig. 5 is an exploded perspective view of a potential sensor of an example 3. On a substrate 204, detection electrode assemblies 321a, 321b, lead electrodes 322a, 322b for detection electrodes, connecting electrodes 323a to 323c, and driving lead electrodes 324a, 324b are formed by patterning. The detection electrode assemblies 321a, 321b are comprised of sets of mutually distanced individual detection electrodes, and the detection electrodes of each set are electrically connected by the lead electrode 322a or 322b for the detection electrodes. Also the individual detection electrodes of the detection electrode assemblies 321a, 321b are arranged with such gaps as not to cause electrical shortcircuiting. Movable shutter units 310a to 310d are formed by mask members 311a to 311d, parallel hinge suspensions 312a to 312d and fixed members 313a to 313d, which are integrally formed with conductive

materials. The connecting electrodes 323a to 323c and the driving lead electrodes 324a, 324b are fixedly coupled with the fixed members 313a to 313d. The mask members 311a to 311d are supported by the parallel hinge suspensions 312a to 312d on the detection electrode assemblies 321a, 321b with a gap thereto. The movable shutter units 310a to 310d are electrically serially connected through the connecting electrodes 323a to 323c and the driving lead electrodes 324a, 324b.

Under the substrate 304, a coil substrate 361 is provided. A flat coil 362 is formed by patterning on the coil substrate 361, and a coil driver 363 supplies the flat coil 362 with a current to generate a magnetic flux in a direction perpendicular to the substrate 304. The driving lead electrodes 324a, 324b are electrically connected to a driver 350, while the lead electrodes 322a, 322b for the detection electrodes are electrically connected with a differential amplifier 390.

Now the function of the potential sensor of the present example will be explained. Fig. 6A is a plan view of the present example. A measured object is positioned in a substantially perpendicular direction to the substrate 304. When a current 861 is generated from the driver 350 as shown in Fig. 6A and is made to flow from the driving lead electrode 324a

to 324b, because of the presence of a magnetic field in a vertically upward direction with respect to the plane of the drawing, the mask members 311a and 311c move to the left in the drawing (arrow 966), while
5 the mask members 311b and 311d move to the right in the drawing (arrow 967). As a result, the detection electrode assembly 321b is exposed to increase an electrostatic capacitance between the detection electrode assembly 321b and the measured object,
10 while the detection electrode assembly 321a is masked to decrease an electrostatic capacitance between the detection electrode assembly 321a and the measured object.

Inversely, when a current 862 is made to flow,
15 as shown in Fig. 6B, in a direction from the driving lead electrode 324b to 324a, the mask members 311a and 311c move to the right in the drawing (arrow 968), while the masks members 311b and 311d move to the left in the drawing (arrow 969). As a result, the
20 detection electrode assembly 321a is exposed to increase an electrostatic capacitance between the detection electrode assembly 321a and the measured object, while the detection electrode assembly 321b is masked to decrease an electrostatic capacitance
25 between the detection electrode assembly 321b and the measured object.

By repeating the above-described operations,

charges of mutually opposite phases are induced in the detection electrode assemblies 321a, 321b and are subjected to a differential amplification, whereby the potential of the measured object can be measured.

5 It is possible, by selecting the drive frequency of the movable shutter units 310a to 310d substantially equal to a mechanical resonance frequency, to reduce an electric power required for driving.

10 The present example can also provide effects similar to those of Example 2. Also the entire structure can be made thin by dispensing with the permanent magnet.

(Example 4)

15 Figs. 7A and 7B illustrate an example 4. Detection electrode assemblies 421a, 421b and movable shutter units 410a to 410d are structured similarly as in Example 3.

As shown in Figs. 7A and 7B, the movable
20 shutter units 410a and 410c are electrically serially connected to a driver 450a, while the movable shutter units 410b and 410d are electrically serially connected to a driver 450b.

When the drivers 450a, 450b generate currents
25 871 and 872 in a direction shown in Fig. 7A, a current in an upward direction in the drawing flows in the movable shutter units 410a and 410d while a

current in a downward direction in the drawing flows in the movable shutter units 410b and 410c. Since currents flowing in a same direction cause a mutual repulsion while currents flowing in opposite
5 directions cause a mutual attraction, the mask members 411a and 411c move to the left in the drawing while the mask members 411b and 411d move to the right in the drawing (arrows 976 and 977). As a result, the detection electrode assembly 421a is
10 masked while the detection electrode assembly 421b is exposed.

Also when the direction of the current generated by the driver 450b is inverted as shown in Fig. 7B, a current in an upward direction in the
15 drawing flows in the movable shutter units 410a and 410b while a current in a downward direction in the drawing flows in the movable shutter units 410c and 410d (arrows 873 and 874). Since currents flowing in a same direction cause a mutual repulsion while
20 currents flowing in opposite directions cause a mutual attraction, the mask members 411a and 411c move to the right in the drawing while the mask members 411b and 411d move to the right in the drawing (arrows 978 and 979). As a result, the
25 detection electrode assembly 421a is exposed while the detection electrode assembly 421b is masked. The potential of the measured object can be measured by

measuring the currents flowing in the detection electrode assemblies 421a, 421b as in Example 3.

Also in this case, it is possible, by selecting the drive frequency of the movable shutter units 410a to 410d substantially equal to a mechanical resonance frequency, to reduce an electric power required for driving.

The present example can also provide effects similar to those of Examples 2 and 3. Also by employing two or more current generating means, it is rendered possible to dispense with the separate magnetic field generating means and to achieve a further compact structure and a lower cost in comparison with Examples 2 and 3.

In Examples 2 to 4, leg portions of fixed member of the movable shutter unit are fixedly connected to the driving lead electrodes or the connecting electrodes, but it is also possible to form a groove portion or the like comprising a guide portion or a slide end defining portion in such electrode and to slidably fit the leg portion of the fixed member therein, whereby the movable shutter unit is rendered slidable between a masking position and an exposing position for the detection electrode. In such case the parallel hinge suspension can be dispensed with in the movable shutter unit. Such configuration can also provide similar effects.

(Example 5)

Fig. 8 is a view showing a part of an image forming apparatus of an example 5. There are shown potential sensors 501a to 501c of the invention, a
5 photosensitive drum 591 commonly employed in an electrophotographic process, and a charger 592. A potential distribution on the photosensitive drum 591 can be measured by monitoring outputs of the potential sensors 501a to 501c in synchronization
10 with the rotation of the photosensitive drum 591. An unevenness in the image can be reduced by controlling an amount of light irradiating the photosensitive drum 591 or controlling the charger 592 according to thus measured potential distribution.

15 The potential sensor of the present invention, being realizable in a small dimension, can be incorporated in a plurality thereby enabling a high precise control.